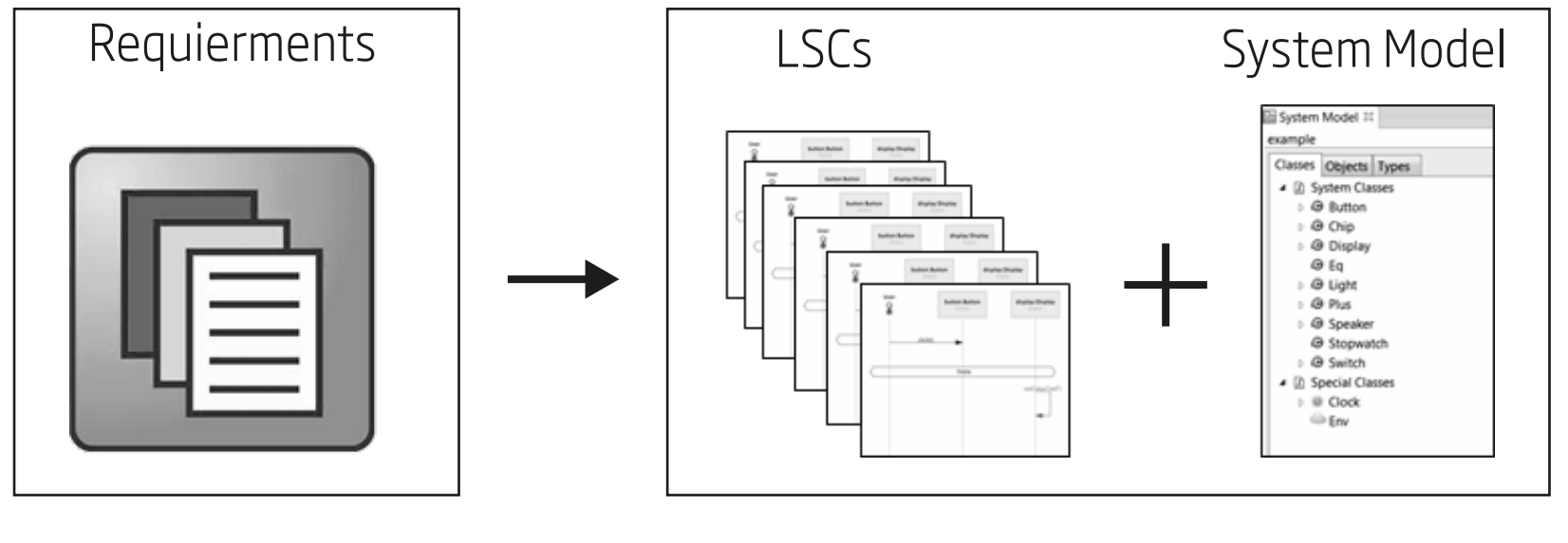


The Challenge

The Task

The Task: Text-to-code generation

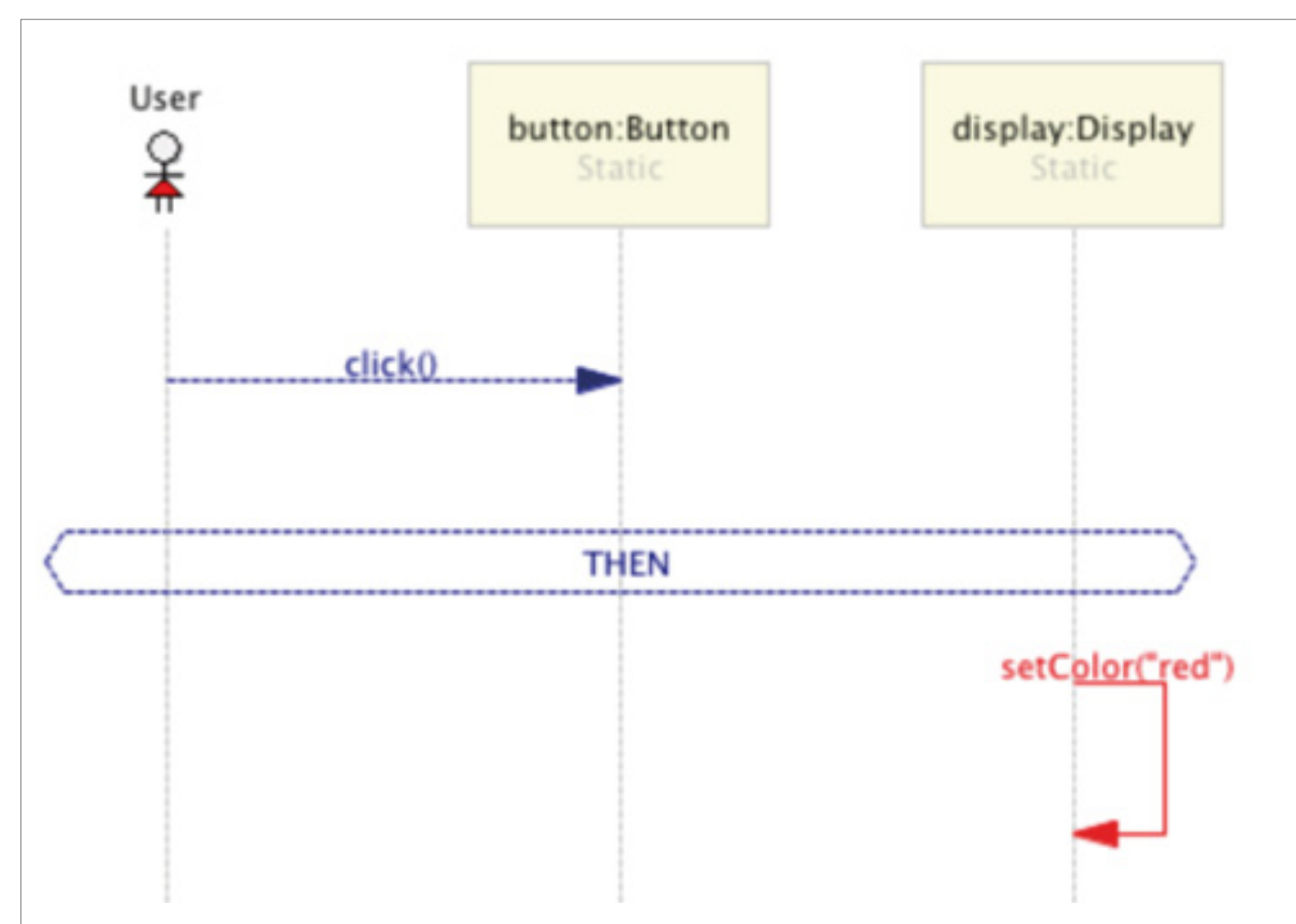
Input: A Requirements Document
Output: A working system



Target Representation

Live Sequence Charts [LSC]

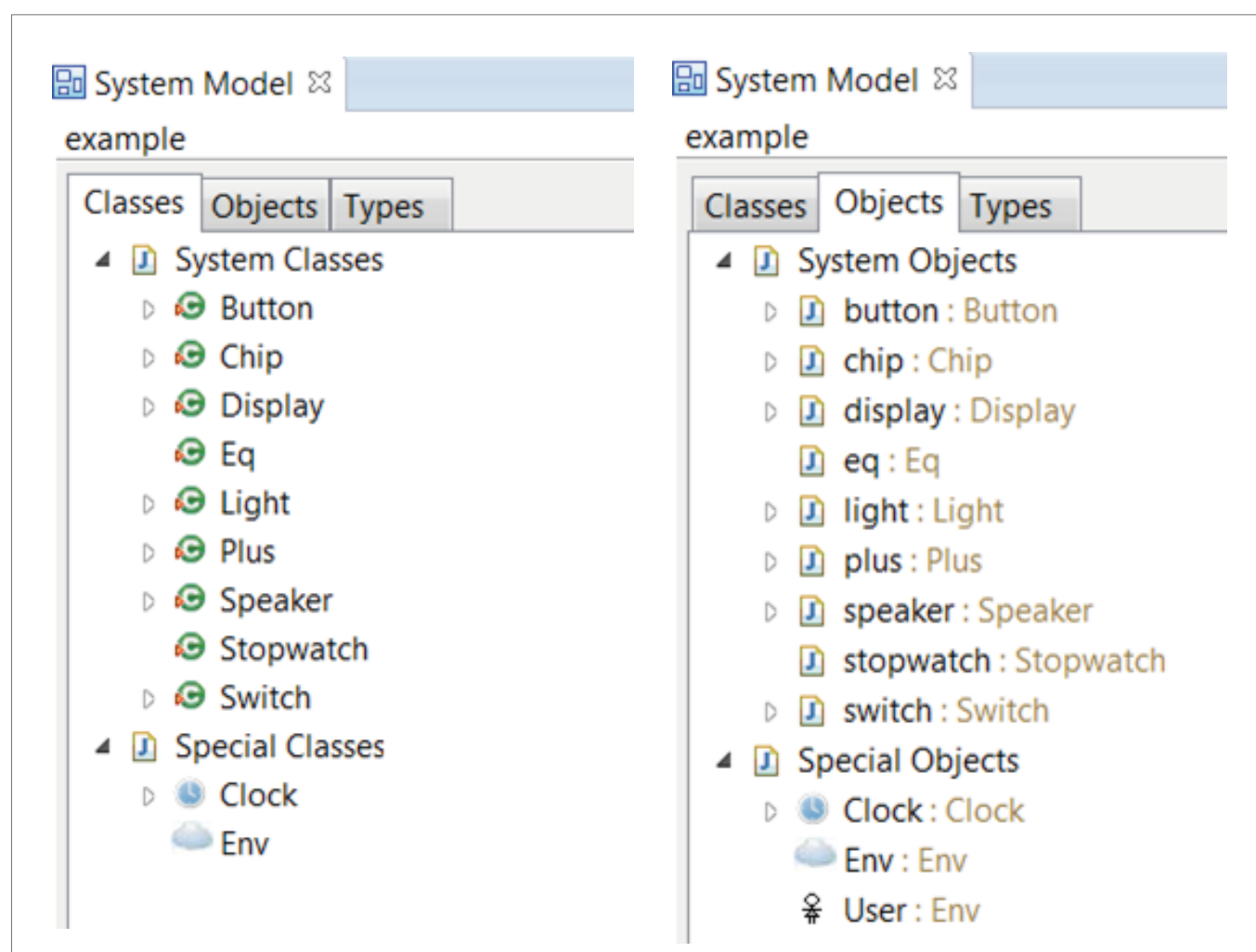
A **live sequence chart (LSC)** describes a possible or necessary run of a specified system. Time in LSCs proceeds from top to bottom. An LSC consists of **lifelines**, **methods**, **modalities**, and **execution status**. LSCs have a direct translation into executable code.



An LSC scenario for the sentence: "When the user clicks the button, the display color must change to red."

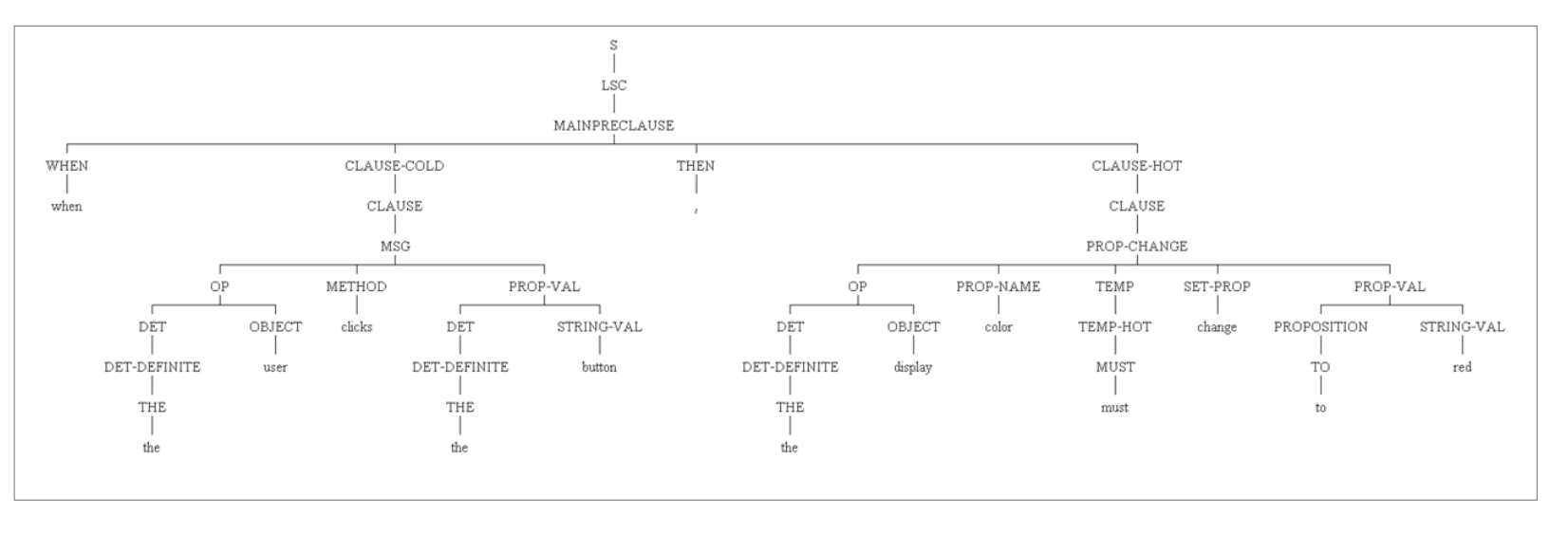
System Model (SM)

A **system model (SM)** presents the implemented architecture. It consists of **objects**, **methods**, **properties** and **values**.



Syntax Tree

A **syntax tree (ST)** is a tree representation of the abstract structure of the requirements according to a context-free grammar (Specifically, the context free grammar specified in [5])



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The Model

The Idea: Use Discourse Context For Disambiguating Individual Requirements

Probabilistic Modeling

"The Probabilistic Model: $f(D) = \text{argmax}_{M \in \mathcal{M}} P(M|D)$

$D \in \mathcal{D}$ is a piece of discourse consisting of an ordered set of requirements.

$M \in \mathcal{M}$ is a code base hierarchy that grounds the semantic interpretation of the requirements.

Noisy Channel Model

The objective function:

$$f(D) = \text{argmax}_{M \in \mathcal{M}} P(M|D) = \text{argmax}_{M \in \mathcal{M}} \frac{P(D|M)P(M)}{P(D)} = \text{argmax}_{M \in \mathcal{M}} P(D|M)P(M)$$

Modeling assumption 1:

$$\text{The source: } P(M) = P(m_1, m_2, \dots, m_n) \approx \prod_i P(m_i | m_{i-1}, \dots, m_{i-k})$$

Modeling assumption 2:

$$\text{The channel: } P(D|M) = P(d_1, d_2, \dots, d_n | m_1, m_2, \dots, m_n) \approx \prod_i P(d_i | m_i)$$

Hidden Markov Model

Assuming a bigram, model our objective function is as follows:

$$f(D) = \text{argmax}_{M \in \mathcal{M}} \prod_i P(m_i | m_{i-1}) P(d_i | m_i)$$

Our model is a hidden markov model (HMM)

- > transition probabilities: represent the gaps between SM snapshots of adjacent requirements.
- > emission probabilities: model the verbal description of each requirement.

The Solution

Parameter Estimation

$$\text{Emission probabilities: } \hat{P}(d_i | m_i) = \frac{\hat{P}(d_i, m_i)}{\hat{P}(m_i)} = \frac{\sum_{t \in T, \text{yield}(t)=d_i, \text{sem}(t)=m_i} \hat{P}(t)}{\sum_{t \in T, \text{sem}(t)=m_i} \hat{P}(t)}$$

$P(t)$ is the probability of a syntax tree.

$m \succ \text{sem}(t)$ means that the LSC semantics of the syntax tree is grounded in the system model m [see formal details in the paper].

We sum the probability of all the trees that derive the requirement d and have LSC semantics that is grounded in the system model m , and normalise it by the sum of all possible trees that their LSC semantics is grounded in m .

We use maximum likelihood estimation (MLE) to learn the tree probabilities $P(t)$:

- > Input: a set of syntactically annotated trees
 - > Output: a probabilistic context free grammar
- We allow for an open-ended lexicon and learn a distribution for unknown-words smoothing.

$$\text{Transition probabilities: } \hat{P}(m_i | m_j) = \frac{\text{gap}(m_i | m_j)}{\sum_{m_j} \text{gap}(m_i | m_j)}$$

where $\text{gap}(\cdot)$ quantifies the information sharing between SM Snapshots.

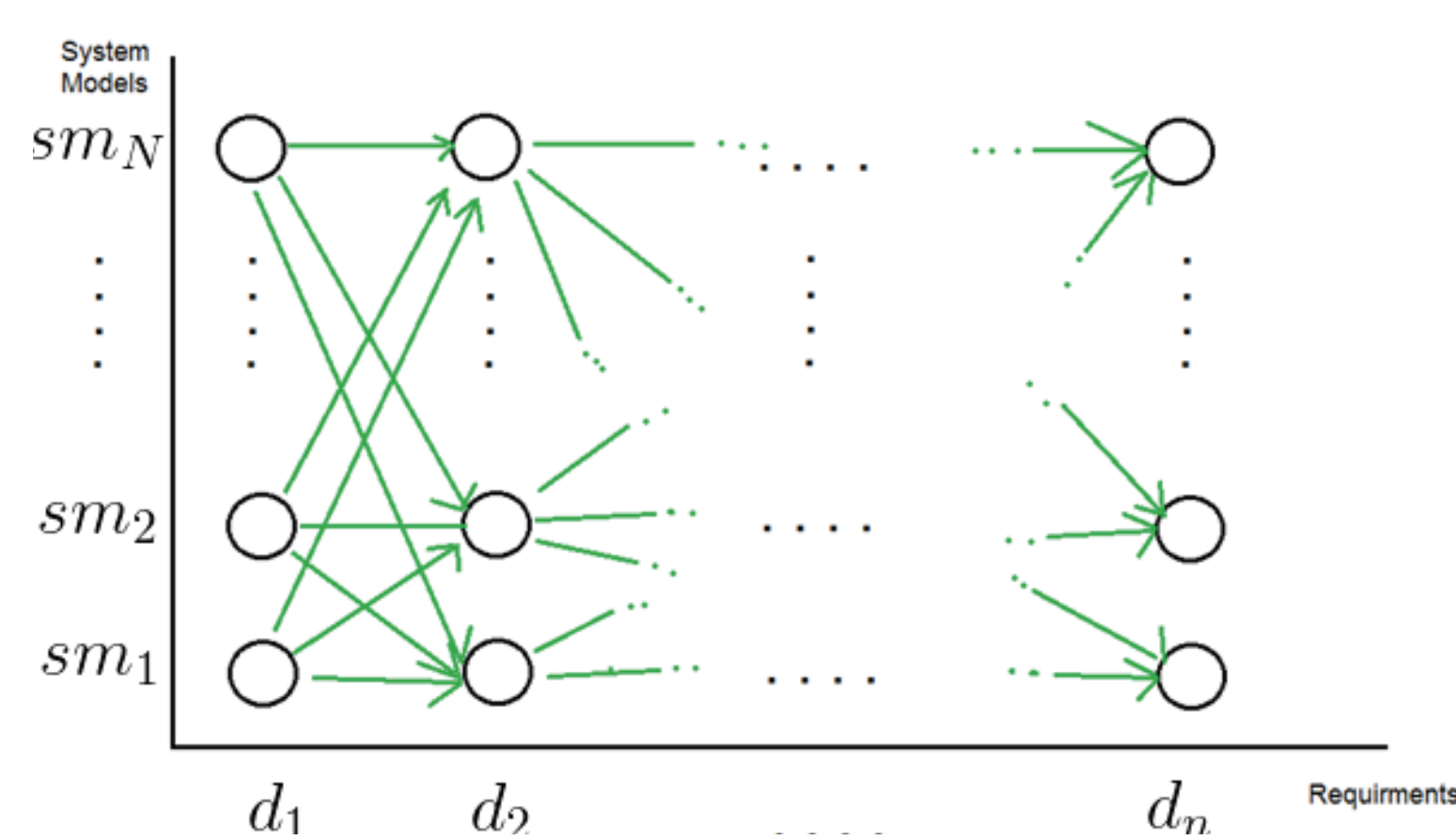
| Transition: | $\text{gap}(m_{curr}, m_{prev})$ |
|---------------|---|
| max-overlap | $ \text{set}(m_{curr}) \cap \text{set}(m_{prev}) $ |
| max-expansion | $1 - \frac{ \text{set}(m_{curr}) \cap \text{set}(m_{prev}) }{ \text{set}(m_{prev}) \cup \text{set}(m_{curr}) }$ |
| min-distance | $1 - \frac{ \text{set}(m_{prev}) + \text{set}(m_{curr}) }{ \text{set}(m_{prev}) \cup \text{set}(m_{curr}) }$ |

The Decoding Algorithm

Recall: Our objective function is

$$f(D) = \text{argmax}_{M \in \mathcal{M}} \prod_i P(m_i | m_{i-1}) P(d_i | m_i)$$

Where $P(m_i | m_{i-1})$ are the transition probabilities in Viterbi (of the arrows), and $P(d_i | m_i)$ are the emission probabilities in Viterbi (of the states).



Finding the most probable path of SM snapshots

$$\text{Viterbi: } \{(d_i, ST_i) | 1 \leq i \leq n\} \rightarrow \{(d_i, st_i) | 1 \leq i \leq n\}$$

- > The algorithm chooses the best syntax tree per requirement by using the context of previous requirements.
- > The context is given by the system model of each possible syntax tree, Using function $g: \text{syntax tree} \rightarrow \text{system model}$
- > Complexity - poly(n, N).

Finding the k-Best syntactic trees for each requirement

$$\text{CKY: } \{(d_1, \dots, d_n), N\} \rightarrow \{(d_i, ST_i) | 1 \leq i \leq n\}$$

- > ST_i is a non-empty set set of syntax trees that returned by CKY, $|ST_i| \leq N$.
- (The algorithm returns the N-best syntax trees per each requirement d_i)
- > Complexity - poly(n, |G|, N, l) where |G| is the size of the grammar, and l is the maximum requirement length over all requirements.

Empirical Evaluation

Experimental Setup

- > Data
 - synthetic (automatically generated) example (10000 requirements)
 - 4 hand-annotated case studies (~100 requirements)
 - * Phone (development set)
 - * Wrist Watch
 - * Chess
 - * Vending Machine
 - * Baby Monitor

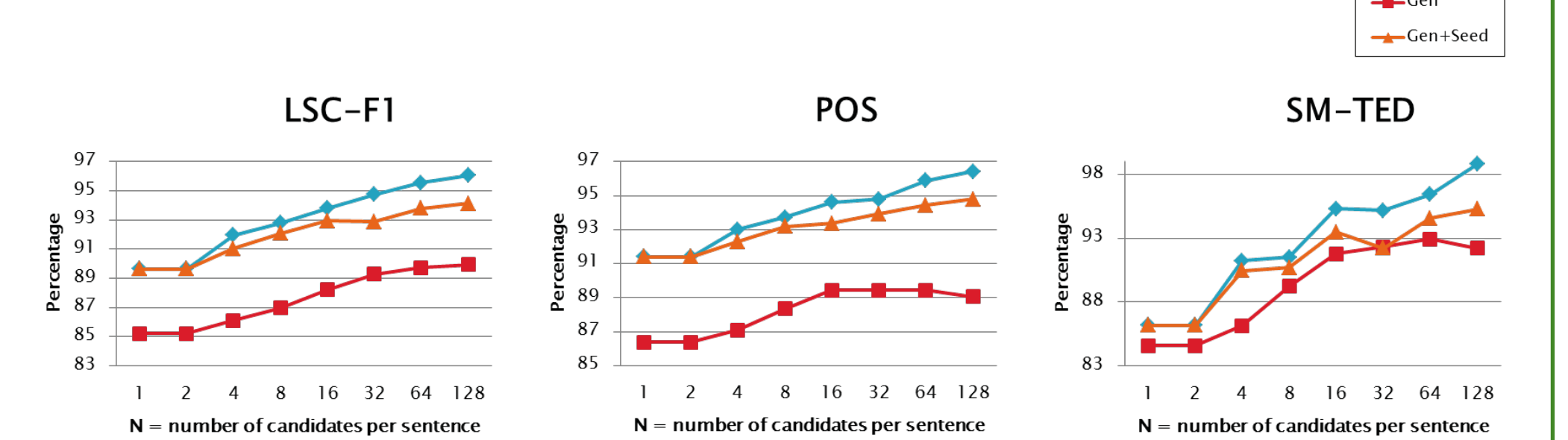
- > Grammar Estimation
 - generated only
 - generated + seed

- > Transition Estimators
 - Max Overlap
 - Max Expansion
 - Min Distance
 - Hybrid mode

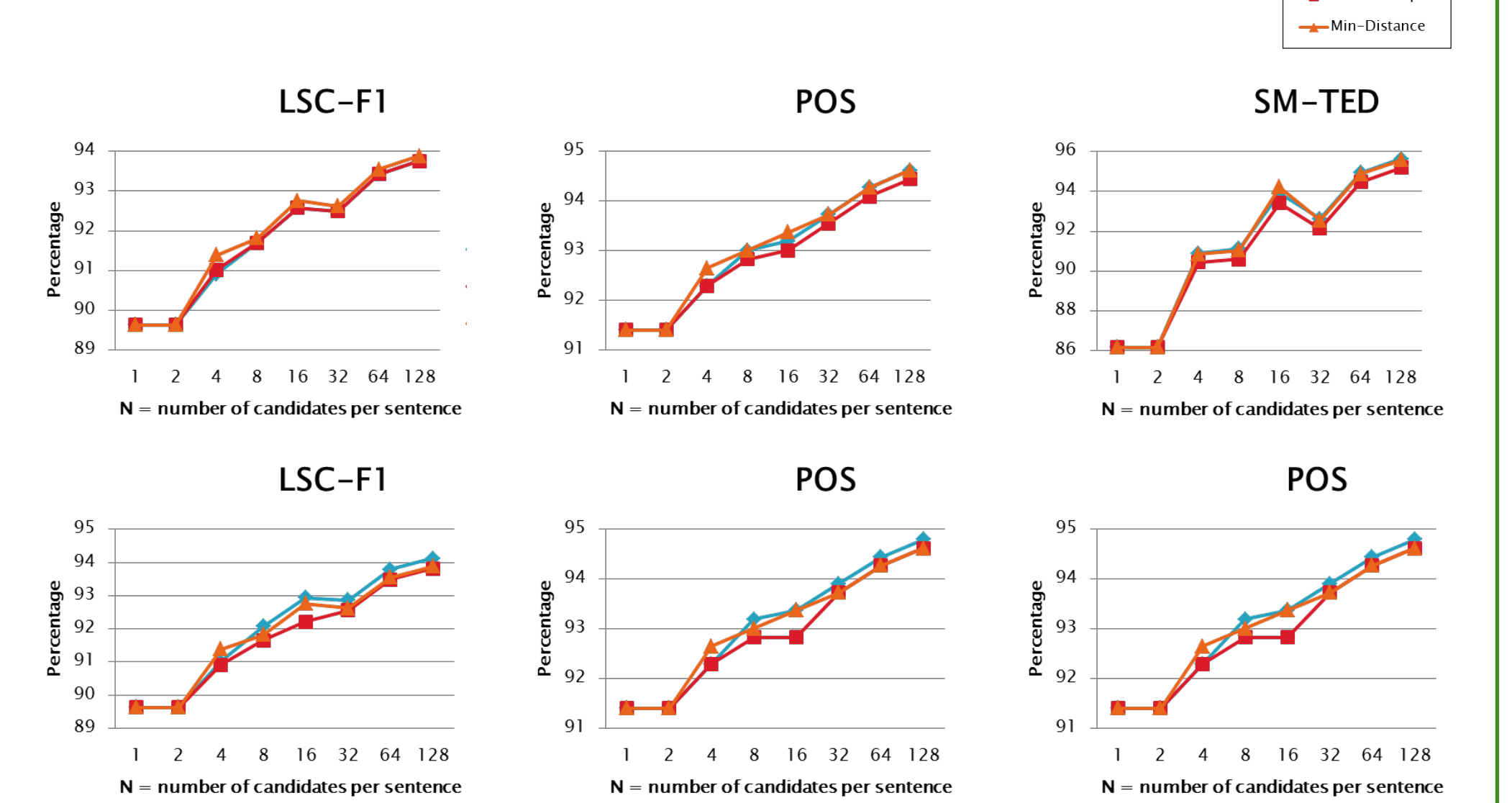
- > Evaluation Metrics

- POS: the accuracy of correctly predicted part-of-speech tags
- LSC-F1: ParsEval [1] on the predicted LSC syntax trees
- SM-TED: Tree-edit distance on the predicted SM trees

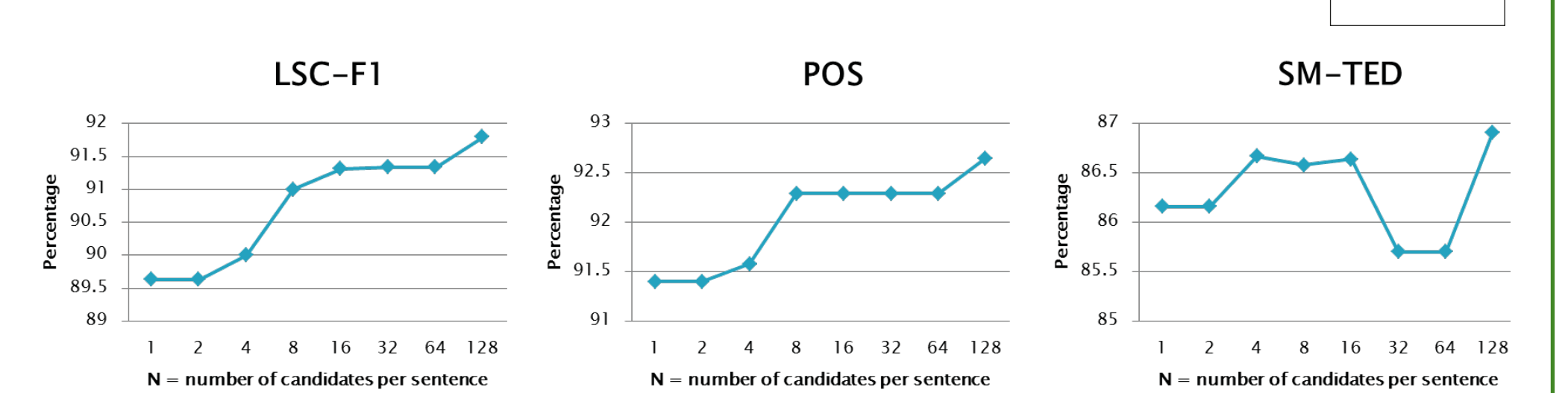
Experiment 1: Grammars (Phone)



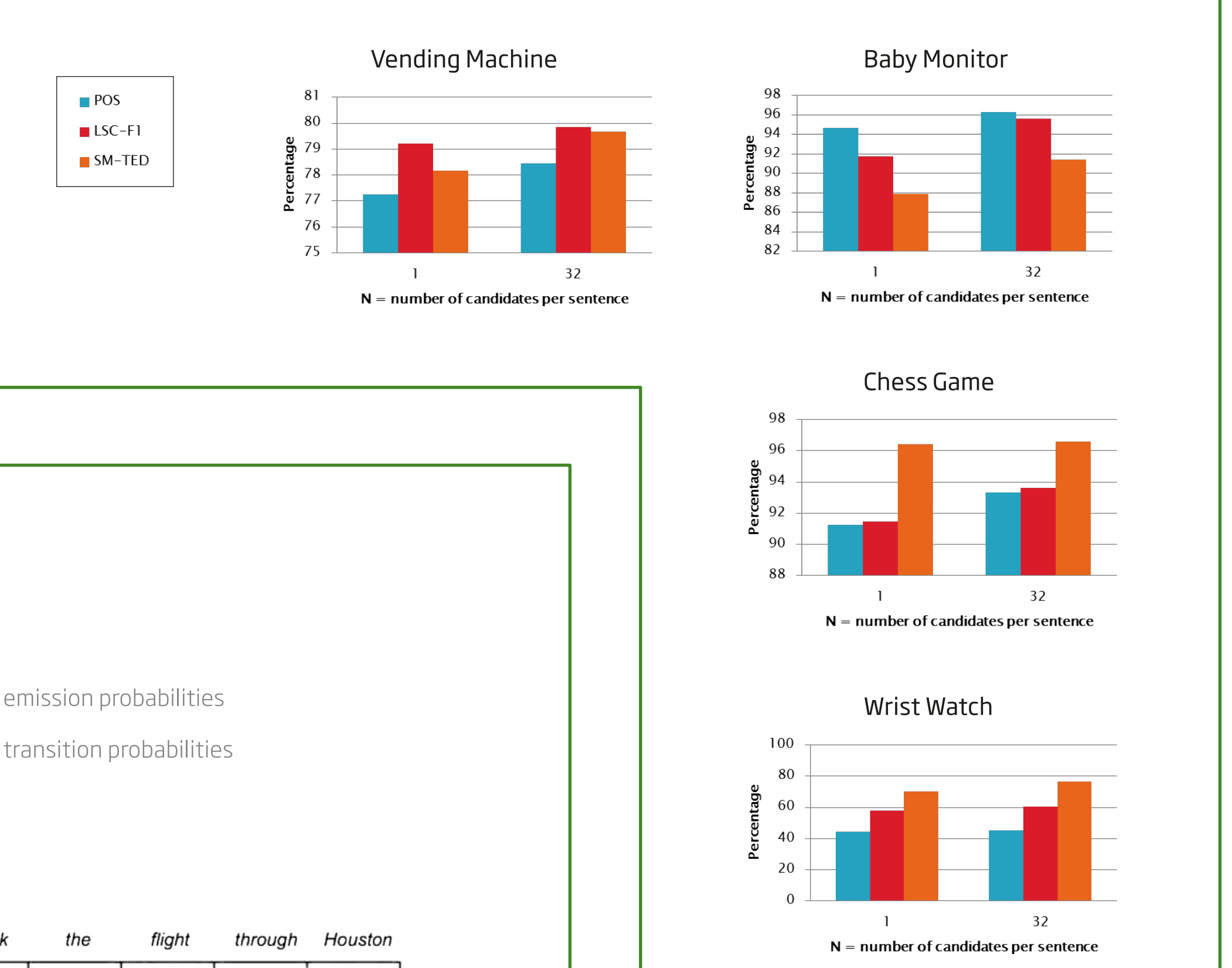
Experiment 2: Transition Types (Phone)



Experiment 3: Context Matters! (Phone)



Experiment 4: Cross-Fold Validation



Future Work

- > Language: CNL \rightarrow NL
- > Modeling: HMM \rightarrow CRF
- > Learning: Generative \rightarrow Discriminative
- > Data: Case studies \rightarrow Real Application